



Validation of specially designed and artificial intelligence-based 3D head model for training of Gasserian ganglion puncture

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GRAPHICAL ABSTRACT

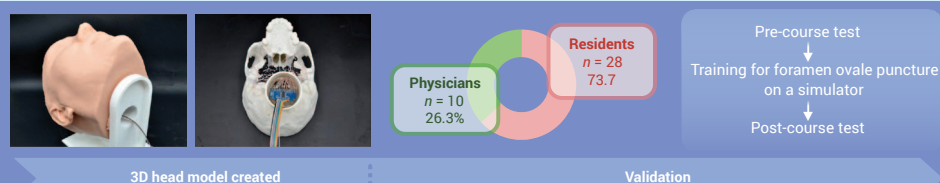


Validation of specially designed and artificial intelligence-based 3D head model for training of Gasserian ganglion puncture

Summary

3D head simulation model for foramen ovale puncture, that is highly realistic and valuable for training, has been developed: procedure time was significantly reduced, the number of puncture attempts decreased, and the incidence of complications involving damage to anatomical structures was lowered.

Materials and methods



Outcomes

Difference in puncture results before and after training

Parameters	Physicians (n = 10)	Residents (n = 28)	Complications associated with	Physicians (n = 10)	Residents (n = 28)
Puncture time, s	- 96 ▼	- 289.2 ▼	Inferior orbital fissure damage, n	- 0.5 ▼	- 1 ▼
Attempts to puncture the foramen ovale, n	- 1.4 ▼	- 4 ▼	Jugular foramen puncture, n	- 1 ▼	- 2 ▼
Total number of complications, n	- 2.6 ▼	- 5.6 ▼	External opening of the carotid canal puncture, n	- 1 ▼	- 2 ▼
			Foramen lacerum puncture, n	- 0.5 ▼	- 1 ▼

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to read



Abstract

Aim. To design, develop and validate a 3D head simulation model for foramen ovale puncture, incorporating computer vision-based artificial intelligence (AI) technologies.

Materials and methods. A 3D simulation model with AI integration was developed in the prototyping laboratory. Its effectiveness for surgical training was evaluated by two groups: neurosurgeons with five or more years of experience ($n = 10$) and residents ($n = 28$). Training outcomes were assessed using the following parameters: intervention time,

number of puncture attempts until they achieved the first one without any complications, number of complications involving critical anatomical structures. The validity was assessed using a Likert scale.

Results. Before the training session, the groups differed in terms of the time spent on the procedure, the number of puncture attempts and the number of complications involving critical anatomical structures. Post-training intervention time decreased by 50% in both groups, the number of puncture attempts reduced by 50.0% in physicians and by 60.3% in residents. The cumulative number of complications declined by 57.8% in physicians and by 59% in residents. Likert scale analysis revealed no statistically significant differences between groups across all parameters. The feasibility and educational effectiveness of the model were rated as 4 or 5 by 90% of participants in both groups. Anatomical realism received a score of 4 or 5 from 90% of physicians and 100% of residents. Radiographic realism received a score of 4 or 5 from all participants. The cost of creating a simulator, excluding the cost of a 3D printer, was 22,685 rubles.

Conclusion. The developed 3D simulation model with AI integration significantly improved training outcomes both in physicians' and residents' groups. The use of standard prototyping equipment provides a cost-effective, radiation-free alternative for widespread implementation in neurosurgical education.

Keywords: computer vision; 3D reconstruction; simulation model; foramen ovale; trigeminal neuralgia; neuronavigation system

MeSH terms:

TRIGEMINAL NEURALGIA – DIAGNOSTIC IMAGING

TRIGEMINAL NEURALGIA – THERAPY

TRIGEMINAL GANGLION – DIAGNOSTIC IMAGING

TRIGEMINAL GANGLION – SURGERY

PUNCTURES – METHODS

IMAGING, THREE – DIMENSIONAL

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Ethics statements. The study was conducted in accordance with the permission of the Local Ethics Committee of Sechenov First Moscow State Medical University (Sechenov University), No 10-25 dated April 24, 2024.

Data availability. The data confirming the findings of this study are available from the authors upon reasonable request. Data and statistical methods used in the article were examined by a professional biostatistician on the Sechenov Medical Journal editorial staff.

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Валидация специально разработанной 3D-модели головы с применением искусственного интеллекта для обучения пункции гассерова узла

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Аннотация

Цель. Спроектировать, разработать и валидировать 3D-модель головы для пункции овального отверстия, используя технологии искусственного интеллекта (ИИ) на основе компьютерного зрения.

Материалы и методы. В лаборатории прототипирования разработана трехмерная симуляционная модель с интеграцией ИИ. Ее эффективность для хирургического обучения оценивалась в двух группах: нейрохирурги с опытом работы пять и более лет ($n = 10$) и ординаторы ($n = 28$). Результаты обучения оценивались по времени вмешательства, количеству попыток пункции до первой попытки без осложнений, количеству осложнений, связанных с повреждением критических анатомических структур. Валидность оценивалась с помощью шкалы Лайкерта.

Результаты. До обучения группы различались по времени, затраченному на вмешательство, количеству попыток пункции и количеству осложнений, связанных с повреждением критических анатомических структур. После обучения время вмешательства сократилось на 50% в обеих группах, количество попыток пункции уменьшилось на 50,0% у врачей и на 60,3% у ординаторов. Общее число осложнений снизилось на 57,8% у врачей и на 59% у ординаторов. Анализ шкалы Лайкерта не выявил статистически значимых различий между группами по всем параметрам. Осуществимость и образовательная эффективность модели были оценены на 4 или 5 баллов 90% участников в обеих группах. Анатомическая реалистичность получила оценку 4 или 5 у 90% врачей и 100% ординаторов. Рентгенографический реализм получил оценку 4 или 5 от всех участников. Стоимость создания симулятора, не учитывая стоимость 3D-принтера, составила 22 685 рублей.

Заключение. Разработанная 3D-симуляционная модель с интеграцией искусственного интеллекта значительно улучшила результаты обучения как в группе врачей, так и в группе ординаторов. Использование стандартного оборудования для прототипирования представляет собой экономически эффективную, безрадиационную альтернативу для широкого внедрения в нейрохирургическое образование.

Ключевые слова: компьютерное зрение; 3D-реконструкция; симуляционная модель; овальное отверстие; невралгия тройничного нерва; система нейронавигации

Рубрики MeSH:

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ТРОЙНИЧНОГО НЕРВА НЕВРАЛГИЯ – ТЕРАПИЯ

ТРОЙНИЧНОГО НЕРВА ГАНГЛИЙ – ДИАГНОСТИЧЕСКОЕ ИЗОБРАЖЕНИЕ
 ТРОЙНИЧНОГО НЕРВА ГАНГЛИЙ – ХИРУРГИЯ
 ПУНКЦИИ – МЕТОДЫ
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Доступ к данным исследования. Данные, подтверждающие выводы этого исследования, можно получить у авторов по обоснованному запросу. Данные и статистические методы, представленные в статье, прошли статистическое рецензирование редактором журнала – сертифицированным специалистом по биостатистике.

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Abbreviations:

AI – artificial intelligence

FO – foramen ovale

GG – Gasserian ganglion

HIGHLIGHTS	КЛЮЧЕВЫЕ ПОЛОЖЕНИЯ
The usage of the Inobitec DICOM Viewer software and Autodesk 3D Max software packages allows you to develop an individual simulator based on the initial MRI and CT DICOM data of the patient for preoperative training foramen ovale puncture in trigeminal neuralgia.	Использование программных пакетов Inobitec DICOM Viewer software и Autodesk 3D Max software позволяет разработать индивидуальный симулятор на основе исходных DICOM данных пациента, полученных при магнитно-резонансной и компьютерной томографии, для предоперационной отработки пункции овального отверстия при невралгии тройничного нерва.
The usage of a conductive filament and an electroactive puncture needle provides immediate feedback, effectively minimizing the risk of the developing incorrect skills in case of trajectory deviation of the puncture needle.	Использование токопроводящего филамента и электроактивной пункционной иглы обеспечивает немедленную обратную связь, что эффективно предотвращает формирование неправильных навыков в случае девиации траектории пункционной иглы.
After training on the simulator undertaken by neurosurgeons (with more than 5 years of experience) and residents, the intervention time, the number of puncture attempts and the frequency of complications significantly decrease.	После обучения на симуляторе нейрохирургов (с опытом более 5 лет) и ординаторов значительно снижается время вмешательства, количество попыток пункции и частота осложнений.

The paradigm of a competency-based surgical education is intrinsically linked to the structured training of specialists [1]. A key strategy for preparing neurosurgical trainees involves combining rigorous theoretical instruction with accessible practical

experience [2]. Today, challenges in literature accessibility are largely addressed through global open-access archives of medical publications [3]. However, the limited duration of residency and the potential for fatal complications arising from intraoperative neurosurgical

errors constrain the acquisition of hands-on surgical skills [4].

In the current literature, little attention is paid to simulation models for training puncture techniques in the treatment of trigeminal neuralgia [5]. D.B. Almeida et al. [6] described a method for creating a model for practicing puncture treatment of trigeminal neuralgia based on a cadaveric skull, in which the authors used a skull with a movable lower jaw actuated by springs, preserved spatial dimensions for the silicone structure, and applied a latex mask to enhance realism. A similar model based on a cadaveric skull was presented by Y.Q. He et al. in 2014 [7], with the distinctive feature of incorporating a silicone Gasserian ganglion (GG).

While cadaveric dissection remains the gold standard for technical training, legal, ethical, and financial constraints have led to a yearly decline in cadaver availability [5]. The active integration of artificial intelligence (AI) and engineering technologies in medicine has transformed approaches to surgical education [8].

The procedural target in trigeminal neuralgia puncture is the GG, which is most safely and effectively accessed via the foramen ovale (FO) of the skull base [9]. Performing GG puncture under radiologic guidance requires additional hand-eye coordination, as it relies on fluoroscopic trajectory alignment without direct visual feedback. However, fluoroscopic guidance limits training time due to the negative effects of ionizing radiation [10]. Emulating C-arm functionality via computer vision technologies can offer a safe and accessible training solution.

Aim of the study: to design, develop and validate a 3D head simulation model for FO puncture, incorporating computer vision-based AI technologies.

MATERIALS AND METHODS

This study consisted of two parts: the design of a 3D head model using AI (01.05–17.06.2024), and the evaluation of its training validity (15.08–01.10.2024).

Part 1. Development of the 3D head model

Pseudonymized magnetic resonance imaging and computed tomography data in DICOM format from one patient with trigeminal neuralgia were utilized to construct the 3D model. A detailed research protocol was developed to guide the modeling of specific anatomical structures: cerebral arteries (based on 3D time of flight magnetic resonance angiography), cranial nerves (fast Spoiled Gradient Echo based on magnetic resonance imaging), and the skull (computed tomography imaging).

Using the Inobitec DICOM Viewer software (Inobitec DICOM Viewer Pro licensed software, Inobitec LLC, Russia), artifact removal and segmentation were performed for the following structures based on native DICOM data: the skull base, contact zones in the skull base region (including the inferior orbital fissure, jugular

foramen, external opening of the temporal carotid canal, lacrimal foramen and spinous foramen), GG, and internal carotid artery (Fig. 1A).

The segmented data were exported in STL format to Autodesk 3D Max software (3ds Max licensed software, Autodesk Inc., USA), where the following elements were modeled: a hinge mechanism to simulate the mobility of the temporomandibular joint, GG (including maxillary, mandibular, and orbital branches), a non-anatomical Meckel's cave (a cavity within the GG aligned with the triangular plexus projection), a tube for housing electronic components, a stand for the 3D head model, a LED screen, negative skin molds for silicone casting, and custom molds for silicone containers (Fig. 1B–F).

Autodesk 3ds Max data were exported to PrusaSlicer software (open-source license, Prusa Research, Czech Republic) to prepare for printing on a Hercules Strong DUO 3D printer (IMPRINTA Russia) with a TwinHot dual extruder head, using fused deposition modeling technology. The resulting file was saved in GCODE format.

Two extruders were used simultaneously to fabricate the skull base. The first extruder, loaded with white ABS plastic, printed the main non-electroactive volume of the skull with 100% filling to simulate the density of the bone structure. The second extruder used electrically conductive black filament U3 Flex Conductive to print the electroactive areas of the skull. The conductive properties of the material were achieved through its composition, which included thermoplastic polyurethane and carbon nanotubes. In addition, 3D models of internal carotid artery and GG were printed using the conductive filament. In contrast, components such as the electronic tube housing, the head model stand, LED screen frame, negative skin molds for silicone casting, and negative molds for tip production were printed with PLA plastic.

To create skin models, the printed silicone molds were treated with a wax-based release spray lubricant. For casting, Ecoflex 00-10, a platinum-based silicone system, was mixed with POLYMER O coloring pigment paste and degassed using a vacuum compressor prior to pouring. The silicone system was poured into the prepared mold. The skin model was bonded to the skull using SIL-POXY, a silicone-based adhesive. For simulation of the dura mater, the Platset 20 silicone system was applied to the inner surface of the skull model. To recreate the Meckel cavity, the negative tip mold was coated with silicone to form a balloon-like structure, which was fixed to the electronic tube with SIL-POXY adhesive. The silicone tube was connected to a 20 mL syringe that delivered pressurized water.

After preparation of all components, the electroactive zones were connected to the electronic unit with flexible copper fluoroplastic-insulated stranded wires. Light and sound signaling of instrument contact detection with electroactive zones of the skull base, as well as with 3D models of the internal carotid artery and GG, was carried

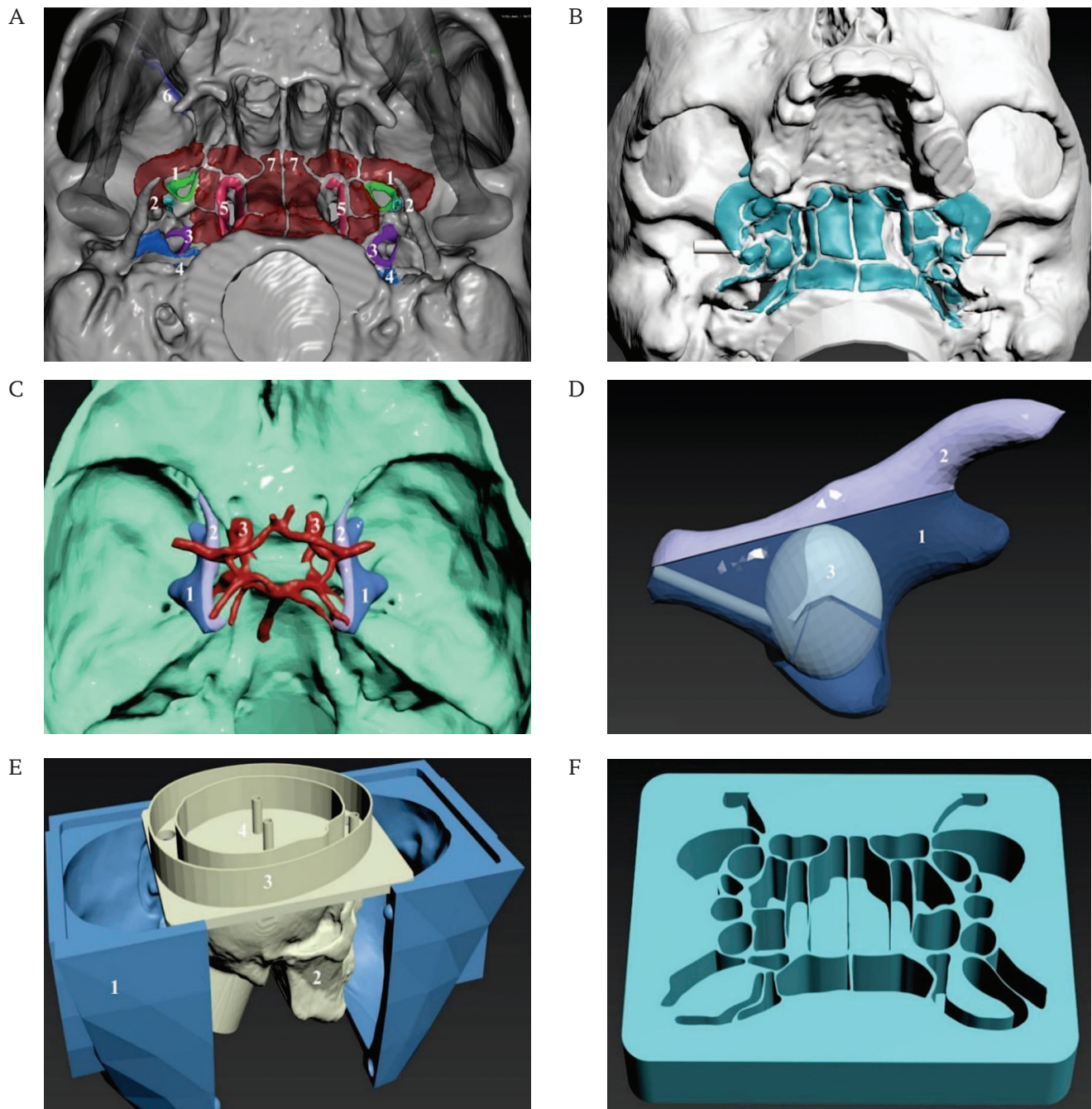


FIG. 1. 3D head model created by Inobitec and Autodesk 3D Max software.

A. The 3D model of the skull base with highlighted contact and non-contact zones (Inobitec software): 1 – foramen ovale (green color), 2 – foramen spinosum (turquoise color), 3 – external opening of the carotid canal (lilac color), 4 – foramen jugulare (blue color), 5 – foramen lacerum (pink color), 6 – inferior orbital fissure (dark blue), 7 – adjacent non-contact zones (red color).

B. The 3D model of the skull base with highlighted contact and non-contact zones (both marked in turquoise, Autodesk 3D Max software).

C. The 3D model of the Gasserian ganglion and internal carotid artery (Autodesk 3D Max software): 1 – maxillary and mandibular zones of the Gasserian ganglion, 2 – ophthalmic branch of the Gasserian ganglion, 3 – internal carotid artery.

D. The 3D model of the Gasserian ganglion with a simulated Meckel's cave (Autodesk 3D Max software): 1 – maxillary and mandibular zones of the Gasserian ganglion, 2 – ophthalmic branch of the Gasserian ganglion, 3 – non-anatomic Meckel's cave (cavity inside the Gasserian ganglion in the triangular plexus projection).

E. The 3D printed form for silicone casting of the external part of the skin in collapsible mold (Autodesk 3D Max software): 1 – 3D printed model of the negative mold for skin filling, 2 – 3D model of the skull for skin filling, 3 – container for additional volume of silicone, 4 – ventilation holes for degassing.

F. The 3D model of the LED screen (Adobe 3D Max software).

out by detecting electrical resistance in the “conductive plastic – puncture needle” circuit (Fig. 2A–F).

In addition to the conductivity of the needle, a special QR code was printed and attached to the end of the needle to apply computer vision technology.

The “conductive plastic – puncture needle” circuit was implemented via a programmable multichannel electronic unit based on Arduino Nano microcontroller (open-source hardware and software platforms, Arduino Software, Italy). Expansion of analog input capacity was achieved using a 16-channel multiplexer (CD74HC4067), while output expansion for LED signal indicators was facilitated using 74HC595 shift registers. LED indication was realized by means of SMD 5730 type LEDs and 15 Ohm current-limiting resistors. A circuit diagram of the 3D head model operation based on the ARDUINO microcontroller is presented in Supplement A (Supplementary materials on the journal’s website <https://doi.org/10.47093/2218-7332.2025.1237-annex-a>).

White LEDs, responsible for detection of the skull base zones, were installed at designated positions on the LED screen, each separated by plastic dividers to minimize the scattering of the light flux around the perimeters of certain zones. Additionally, green LED (Led1) and red LED (Led2) were mounted at the base of the LED screen to indicate puncture needle contact with the GG and internal carotid artery, respectively. The total cost of consumables was 22,685 rubles.

The time spent on modeling was 5 days, production of the 3D model – 2 days, work with electronics and programming – 4 days. The total cost of consumables was 22,685 rubles (Supplementary materials on the journal’s website <https://doi.org/10.47093/2218-7332.2025.1237-annex-b>).

Finally, a portable neuronavigation system was developed to reduce radiation exposure for trainees. To simulate the puncture intervention, an integrated hardware-software complex utilizing computer vision technologies was employed. Video tracking of the surgical instrument was achieved by detecting fractal markers in the form of QR codes affixed to the instrument. The streaming image was captured and transferred to a personal computer, where it was processed using the PLUS Server application (open-source software, Plus Toolkit Community and PerkLab) [11]. In this system, AI algorithms convert the incoming video stream into a matrix of spatial coordinates. These coordinates are subsequently transferred to a dedicated visualization platform – 3D Slicer software (open-source license) [12]. The resulting spatial data were mapped onto a virtual environment within 3D Slicer, where the coordinates were assigned to a 3D model of the surgical instrument. This allowed dynamic visualization of its interaction with the 3D training model of the head on the monitor screen. Two essential models were integrated

into the 3D Slicer environment: the virtual surgical instrument and the static head model, reconstructed from patient-specific DICOM data. The head model is static, while the surgical instrument moved in real time according to the physical instrument’s position, thereby simulating C-arm-like visualization during the simulated procedure (Fig. 3).

Part 2. Validation of the training model of the foramen ovale puncture simulator

A total of 38 participants, 10 experts (neurosurgeons with more than 5 years of experience) of the Federal Center of Neurosurgery (Tyumen) and 28 residents of the Department of Neurosurgery of the Sechenov First Moscow State Medical University (Sechenov University), whose clinical site is located at Federal Center of Neurosurgery, underwent the simulation program (Fig. 4).

Inclusion criteria:

- age from 23 to 60 years;
- theoretical knowledge of the topographic anatomy of the skull base;
- theoretical knowledge of the radiographic orientation of the FO of the skull;
- no prior involvement in the development of the simulation model;
- a written voluntary informed consent to participate in the study.

Non-inclusion criterion:

- mental disorders affecting learning ($n = 0$).
- The training took place in a laboratory setting is presented in the video file Supplement C (Supplementary materials on the journal’s website <https://doi.org/10.47093/2218-7332.2025.1237-annex-c>).

The results of the FO puncture were evaluated before and after training period using the following parameters:

- intervention time;
- number of puncture attempts;
- number of complications during the puncture involving anatomical structures located at the skull base (the inferior orbital fissure, jugular foramen, external opening of the temporal bone carotid canal, foramen lacerum, and foramen spinosum) as well as in the region of the middle cranial fossa (the first branch of the trigeminal nerve and the cavernous segment of the internal carotid artery).

Before and after training, each participant performed a series of puncture attempts until they achieved the first one without any complications. Once this had been achieved, they stopped and recorded the result. The maximum number of attempts was limited to ten.

Also, participants completed a post-training questionnaire based on a Likert scale to access the perceived feasibility and educational value of the simulator, the anatomical realism of landmarks and radiographic realism with scores: strongly agree (5), agree (4), neutral (3), disagree (2), strongly disagree (1) [13].

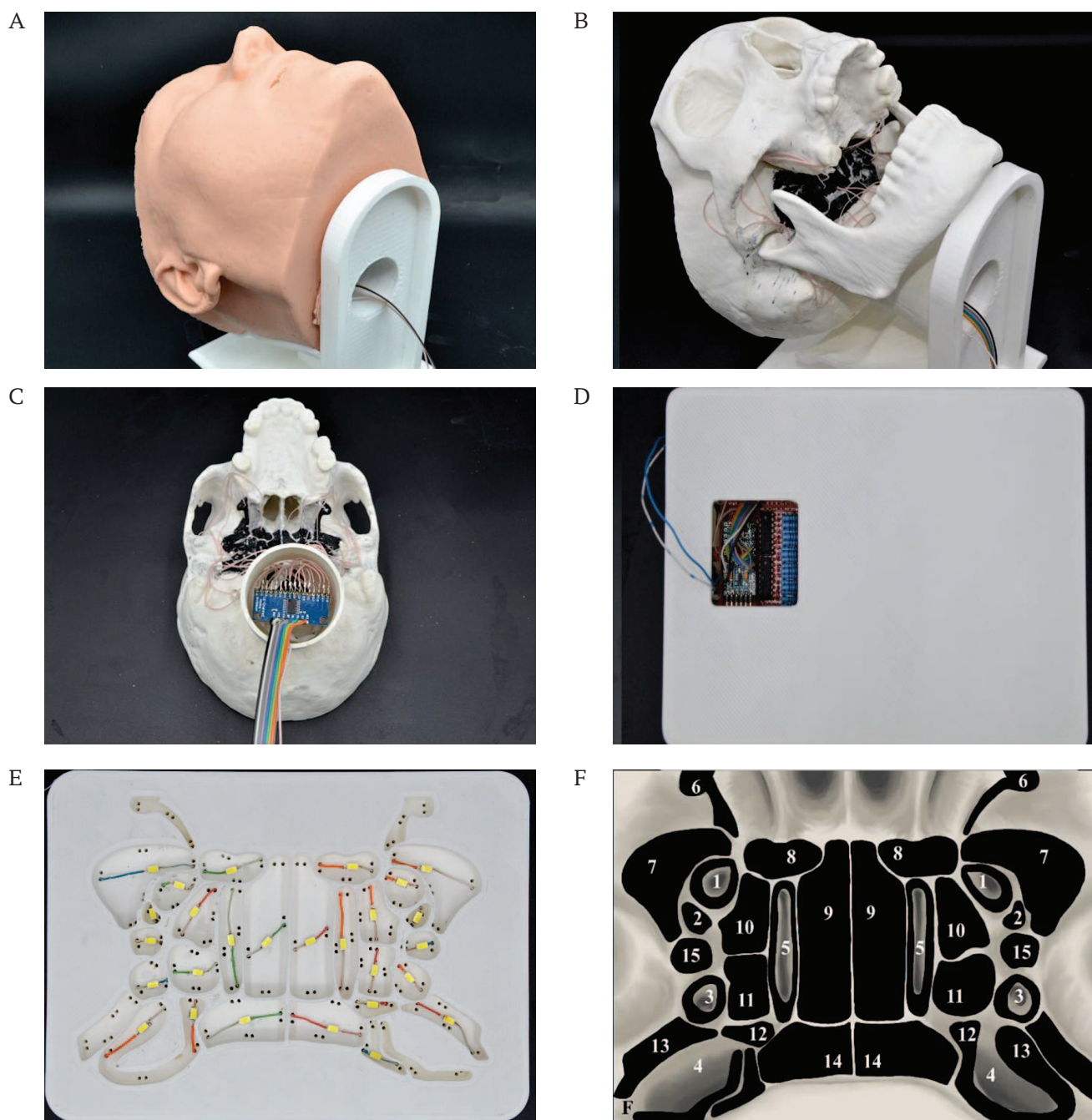


FIG. 2. The electronic part of the 3D head model for practicing foramen ovale puncture.

A. The silicone 3D head model with electronics unit.

B. The 3D printed head model with electroactive zones printed with black U3 Flex Conductive filament.

C. The electronics block of a 3D skull model based on ARDUINO microcontroller.

D. The electronics block of the LED screen based on ARDUINO microcontroller.

E. The LED screen.

F. The scheme of the LED screen: 1 – foramen ovale, 2 – foramen spinosum, 3 – external opening of the carotid canal, 4 – foramen jugulare, 5 – foramen lacerum, 6 – inferior orbital fissure, 7–14 – adjacent non-contact zones.

Statistical analysis

Descriptive statistics were reported as absolute frequencies and percentages for categorical variables, and as medians with interquartile ranges (25th; 75th percentile) for ordinal or non-normally distributed continuous variables. For normally distributed continuous variables,

data were expressed as mean with standard deviation. Normality was assessed with the Shapiro–Wilk test and verified visually using Q–Q plots and histograms.

The median values were calculated from multiple puncture attempts performed by each participant within each training phase, and then group medians

with interquartile ranges were determined across all participants in each group. Between-group comparisons were performed with a two-tailed independent Student's *t*-test for normally distributed data or the Mann-Whitney *U*-test for non-normally distributed data. Comparisons of paired data before and after training were performed using the paired Student's *t*-test for normally distributed differences or the Wilcoxon signed-rank test for non-normally distributed differences. Five-level Likert responses were compared between groups with the two-sided Fisher-Freeman-Halton exact test (5×2 contingency tables). For sensitivity analysis, Likert scores were dichotomized ($\geq$ "Agree" vs. $\leq$ "Neutral"), and a two-sided Fisher's exact test (2×2) was applied. All tests were two-tailed, and a *p*-value < 0.05 was considered statistically significant. Statistical analyses were conducted in R version 4.5.1 (R Foundation for Statistical Computing, Vienna, Austria).

RESULTS

Analysis of puncture performance before and after training revealed statistically significant improvement across all evaluated parameters in both groups (Table). Following the training, puncture time was reduced by approximately half in both groups. The number of puncture attempts before the first successful, complication-free attempt was reduced by 50% in the physicians' group and by 60.3% in the residents' group.

The total number of complications after training decreased by 57.8% in the physicians' group and by 59.0% in the residents' group. Initial complication rates associated with inferior orbital fissure damage, jugular foramen puncture and puncture of external opening of

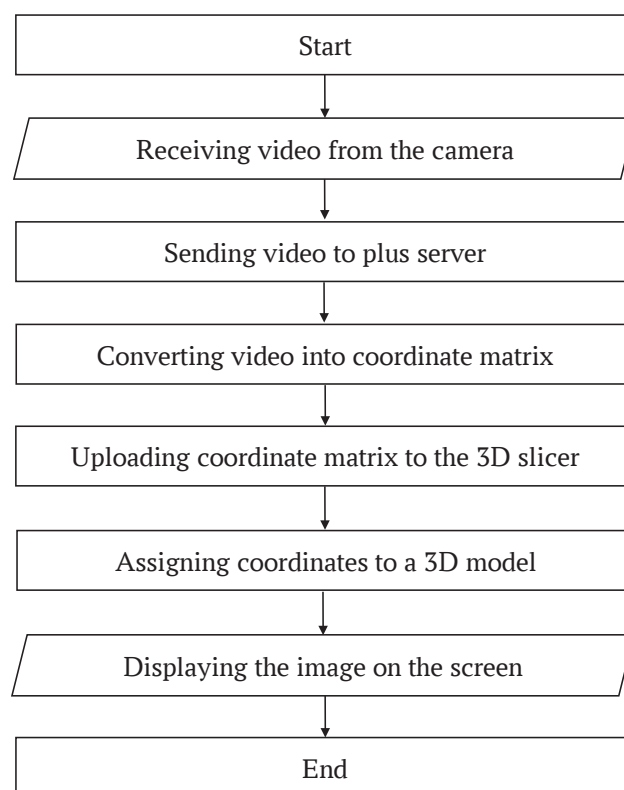


FIG. 3. The block diagram of computer vision technology.

the carotid canal were higher in the residents' group. While initial frequency of other complications (foramen lacerum puncture, puncture of the first branch of the trigeminal nerve, puncture of the internal carotid artery and foramen spinosum puncture) was low and similar both in physicians' and residents' groups (Table).

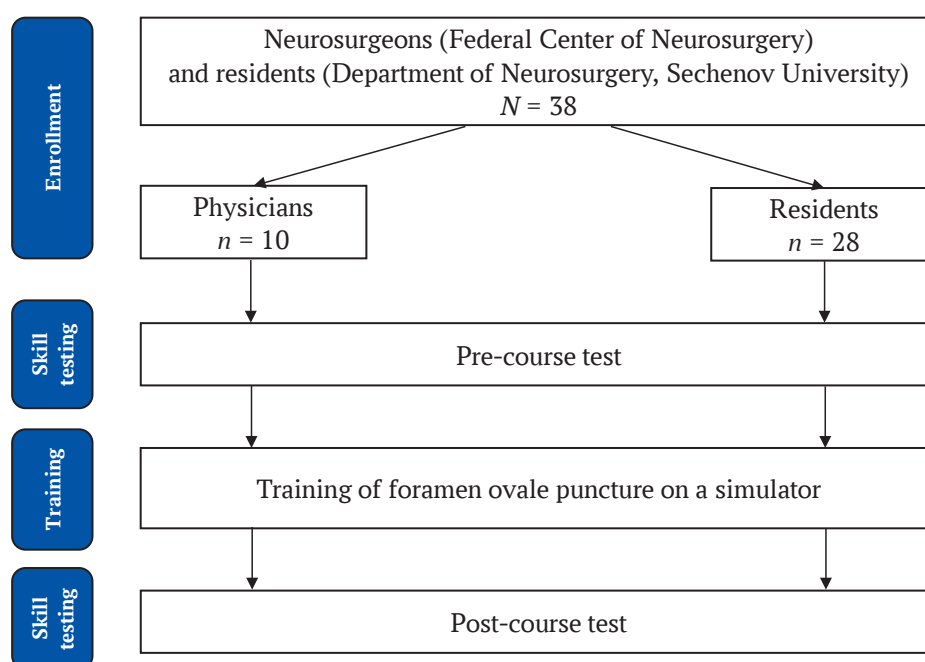


FIG. 4. Study flowchart.

Table. Puncture results before and after training

Parameter	Physicians (<i>n</i> = 10)		<i>p</i> value	Residents (<i>n</i> = 28)		<i>p</i> value
	Before	After		Before	After	
Puncture time, s	186.0 ± 77.2	90.0 ± 51.0	<0.001	527.1 ± 135.0 ^b	237.9 ± 82.4 ^b	<0.001
Attempts to puncture the foramen ovale, <i>n</i>	2.8 ± 0.8	1.4 ± 0.5	<0.001	6.6 ± 2.1 ^b	2.6 ± 1.0 ^b	<0.001
Total number of complications, <i>n</i>	4.5 ± 1.6	1.9 ± 0.7	<0.001	9.5 ± 3.3 ^b	3.9 ± 1.7 ^b	<0.001
Complications associated with:						
inferior orbital fissure damage, <i>n</i>	0.5 (0; 1.75)	0 (0; 0)	n.s.	2 (0.75; 3) ^a	1 (1; 2) ^b	<0.05
jugular foramen puncture, <i>n</i>	1 (0.25; 1)	0 (0; 1)	n.s.	3 (2; 4) ^b	1 (1; 2) ^b	<0.001
external opening of the carotid canal puncture, <i>n</i>	1 (0.25; 1)	0 (0; 0)	<0.05	2 (1; 3) ^a	0 (0; 0)	<0.001
foramen lacerum puncture, <i>n</i>	0.5 (0; 1)	0 (0; 1)	n.s.	1 (0; 2)	0 (0; 1)	<0.001
foramen spinosum puncture, <i>n</i>	0 (0; 0)	0 (0; 0)	n.s.	0 (0; 1)	0 (0; 0.25)	n.s.
puncture of the first branch of the trigeminal nerve, <i>n</i>	0.5 (0; 1)	0 (0; 0.75)	n.s.	0 (0; 1)	0 (0; 0.25)	n.s.
internal carotid artery puncture, <i>n</i>	0 (0; 1)	0 (0; 0.75)	n.s.	0 (0; 1)	0 (0; 0)	n.s.

Notes: ^a*p* < 0.05, ^b*p* < 0.001 when compared to a group of physicians at the same point of the study.
n.s. – not significant.

Following training, the complication rate related to puncture of the external opening of the carotid canal decreased by 88.9% in physicians and by 94.9% in residents, resulting in no statistically significant difference between the two groups post-training (Table). Complications related to puncture of the inferior orbital fissure and jugular foramen decreased by 75.0% and 50.0%, respectively, in physicians, and by 35.3% and 51.9%, respectively, in residents; however, the rates among residents remained significantly higher compared to those of physicians. Other puncture-related complications decreased as follows: foramen lacerum – by 42.9% in physicians and 68.4% in residents; foramen spinosum – by 0% and 44.4%, respectively; first branch of the trigeminal nerve – by 50.0% and 27.3%; internal carotid artery – by 40.0% and 50.0%. Post-training complication rates for these structures were comparable between physicians and residents.

The feasibility and construct validity of the simulator was confirmed by the Likert scale. Both groups rated the simulator as “useful for educational purposes” and “realistic” from anatomical and radiographic points of view.

The perceived feasibility and educational value of the simulator, the anatomical realism of landmarks and radiographic realism, assessed by the Likert scale, received equivalent ratings from both the physicians’ group and the residents’ group (Fig. 5).

DISCUSSION

Various puncture-based interventions for trigeminal neuralgia share a common technical approach: accessing the GG via FO puncture [14]. Despite the technical simplicity of performing FO puncture, the lack of surgical skills may lead to serious complications [15].

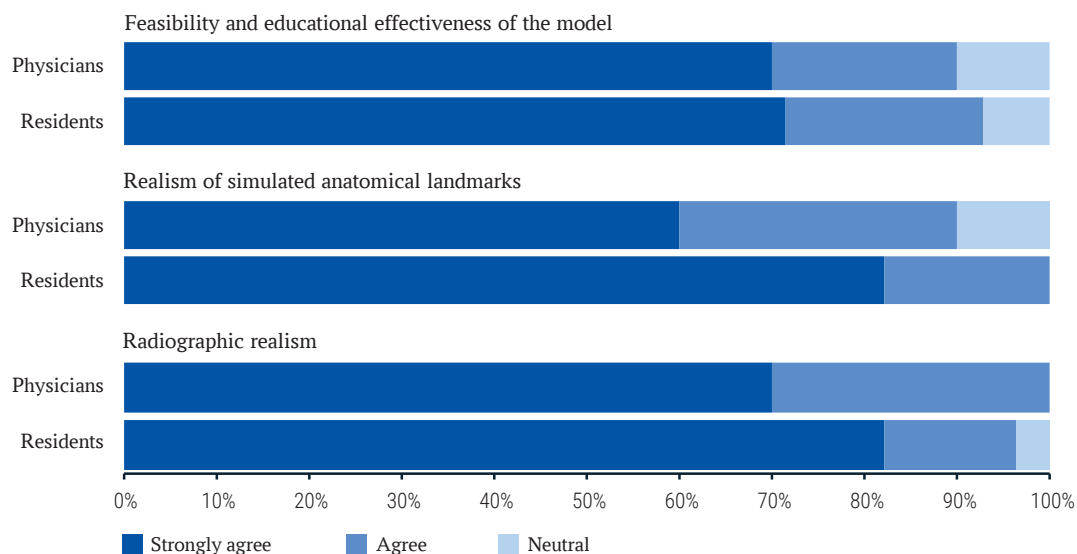


FIG. 5. The training results according to the Likert scale.

The iatrogenic nature of such complications is most frequently attributed to the surgeon's insufficient competence, leading to anatomical disorientation and difficulty maneuvering the puncture needle under fluoroscopic control, primarily due to inadequate hand-eye coordination [10]. To improve a surgeon's competence in puncture-based interventions, it is necessary to provide quality preoperative training in a safe environment [16].

The present study demonstrated the effectiveness of integrating engineering technology and AI in creating a 3D simulator for teaching FO puncture in the treatment of trigeminal neuralgia. The high Likert scale scores for the educational effectiveness of the simulator (70.0–71.4% of participants selected the maximum score), realistic anatomical landmarks (60.0–82.1%) and radiological visualization (70.0–82.1%) confirm the high quality of the developed model. The results of this study showed a statistically significant improvement in all evaluated parameters in both groups of participants after training on the developed model.

The most encouraging result was a 50% reduction in intervention time in both groups after simulation training despite a significant difference in pre-training scores (difference between physicians and residents 341.1 sec), indicating the development of sustainable practical skills regardless of the participants' initial training level. Equally important, a reduction in the number of puncture attempts by 50% in physicians and 60.3% in residents indicates improved accuracy in performing the procedure. The more pronounced improvement in the resident group may be due to the greater potential for skill development in less experienced professionals, consistent with the concept of a learning curve in surgery [17, 18].

The results of this study showed a significant reduction in the total number of complications (around 60% in both groups), which is a key indicator of the clinical relevance of the developed simulator. A more detailed analysis of the types of complications showed that the greatest improvement was observed for puncture of the foramen jugulare, inferior orbital fissure and external carotid orifice in the resident group. Notably, the initially higher complication rates in the resident group approached those of experienced physicians for most parameters after training. The exceptions were puncture of the first branch of the trigeminal nerve and internal carotid artery, where differences between groups were minimal both before and after training. This observation indicates the formation of hand-eye coordination skills and a more accurate understanding of the trajectory of the puncture needle in the areas of the skull base. Formation of the skill of hand-eye coordination in performing various types of surgical interventions has received much attention in the literature [6, 19–21]. The 3D model developed in this study accurately reproduces the anatomical location of the FO, functionally significant

areas of the skull base, GG and internal carotid artery. Moreover, the use of electrically conductive carbon nanotube materials to create feedback zones provides immediate tactile and visual confirmation of contact with critical anatomical structures, which helps prevent the formation of incorrect motor skills and improves the overall quality of learning.

Training of hand-eye coordination for FO puncture usually requires fluoroscopic guidance with a C-arc, which limits training time due to the negative effects of ionizing radiation [22]. Integrating computer vision into the training of FO puncture on a 3D printed model in our study provides a safe and effective alternative [23–25]. In this study, we developed a computer vision algorithm to detect a QR code attached to the puncture needle, thereby mimicking the functionality of the C-arm and enabling the acquisition of hand-eye coordination skills during FO puncture. Using QR code to track the instrument and creating a virtual environment in the 3D Slicer provides a safe alternative to fluoroscopic guidance, which is especially important for repeated training sessions. Another significant advantage of the developed system is its dependence on standard equipment (webcam and personal computer with graphics processor), which makes it affordable for wide implementation in training centers. The elimination of expensive X-ray equipment significantly reduces the overall cost of training, which opens up opportunities for scalable training.

Excluding the cost of a 3D printer, the cost of creating a simulator is significantly lower than the cost of purchasing and storing cadaver material. For instance, the price of a single cadaveric human head is between \$600 and \$1000 in the US, Russia and Italy [26–28]. Despite the fact that cadaveric material is the most suitable for training, access to cadaveric heads is limited by thanks to legal and financial restrictions [29]. In addition, the costs of maintaining anatomical laboratories are very high and the establishment of a cadaveric laboratory requires the resolution of a number of issues regarding its location, the acquisition of instruments, the purchase, storage and disposal of cadaveric material, as well as strict inter-institutional co-operation to resolve legislative aspects, which limits the use of this material in the modern educational process [30, 31].

Limitations of the study and further research perspectives

The study had a limited sample size (38 participants), which may reduce the statistical significance of the results and their generalizability to a wider population of learners. The model is based on data from a single patient with trigeminal neuralgia, which does not take into account anatomical variations between different patients and may limit the realism of the training process.

Further development of this topic could include the creation of a library of 3D models based on different anatomical variants of the FO to increase the versatility

of the simulator, as well as multicenter randomized controlled trials to assess the impact of simulation training on clinical outcomes and patient safety in real-world practice.

CONCLUSION

The conducted study emphasizes the effective integration of engineering technology and AI as a useful and safe tool for teaching puncture-based treatment of trigeminal neuralgia. The results of the study demonstrate that the developed 3D head simulation

model is highly realistic and educationally valuable, supported by both quantitative outcomes and qualitative assessments. Procedure time was significantly reduced, the number of puncture attempts decreased, and the incidence of complications involving damage to anatomical structures was lowered. The use of available equipment and open source software solutions makes this technology scalable for widespread implementation in educational institutions, which can significantly improve the quality of neurosurgeon training and, ultimately, patient safety.

AUTHORS CONTRIBUTIONS

Albert A. Sufianov, Rinat A. Sufianov and Nargiza A. Garifullina developed the idea for the research and its design. Albert A. Sufianov, Nargiza A. Garifullina and Margarita F. Chakhmakhcheva performed the scientific literature search and collected the primary data. Aleksandr N. Zyryanov and Anton D. Zakshauskas developed the 3D model and neuronavigation system. Albert A. Sufianov, Rinat A. Sufianov, Nargiza A. Garifullina and Margarita F. Chakhmakhcheva participated in the writing and editing of the manuscript. All authors approved the final version of the article.

ВКЛАД АВТОРОВ

А.А. Суфианов, Р.А. Суфианов и Н.А. Гарифуллина разработали основную концепцию и дизайн исследования. А.А. Суфианов, Н.А. Гарифуллина и М.Ф. Чахмахчева выполнили научный поиск литературы и сбор первичных данных. А.Н. Зырянов и А.Д. Закшаускас разработали 3D-модель и систему нейронавигации. А.А. Суфианов, Р.А. Суфианов, Н.А. Гарифуллина и М.Ф. Чахмахчева принимали участие в написании основного текста и редактировании статьи. Все авторы утвердили окончательную версию публикации.

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